



Mapping the Stellar Kinematics in the Central 240 pc of M87 with the James Webb Space Telescope

Refa M. Al-Amri¹ , Jonelle L. Walsh¹ , Emily R. Liepold² , Chung-Pei Ma^{2,3} , and Jenny E. Greene⁴ ¹ George P. and Cynthia Woods Mitchell Institute for Fundamental Physics and Astronomy, and Department of Physics and Astronomy, Texas A&M University, College Station, TX 77843, USA; refaalamri@tamu.edu² Department of Astronomy, University of California, Berkeley, CA 94720, USA³ Department of Physics, University of California, Berkeley, CA 94720, USA⁴ Department of Astrophysical Sciences, Princeton University, 4 Ivy Lane, Princeton, NJ 08544, USA

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Abstract

The supermassive black hole (SMBH) in the giant elliptical galaxy M87 is one of the most well studied in the local Universe, but the stellar- and gas-dynamical SMBH mass measurements disagree. As this galaxy is a key anchor for the upper end of the SMBH mass–host galaxy relations, we revisit the central $3'' \times 3''$ ($\sim 240 \times 240$ pc) region of M87 with the Near Infrared Spectrograph (NIRSpec) integral field unit (IFU) on the James Webb Space Telescope. We implement several improvements to the reduction pipeline and obtain high-signal-to-noise ratio spectra ($S/N \sim 150$) in single $0''.05$ spaxels across much of the NIRSpec field of view. We measure the detailed shape of the stellar line-of-sight velocity distribution, parameterized by Gauss–Hermite moments up to h_8 , in ~ 2800 spatial bins, substantially improving upon the prior high-angular-resolution studies of the M87 stellar kinematics. The NIRSpec data reveal velocities with $V \sim \pm 45$ km s⁻¹, velocity dispersions that rise sharply to ~ 420 km s⁻¹ at a projected radius of $0''.45$ (36 pc), and a slight elevation in h_4 toward the nucleus. We comprehensively test the robustness of the kinematics, including using multiple velocity template libraries and adopting different polynomials to adjust the template spectra. We find that the NIRSpec stellar kinematics seamlessly transition to recently measured large-scale stellar kinematics from optical Keck Cosmic Web Imager (KCWI) IFU data. These combined NIRSpec and KCWI kinematics provide continuous coverage from parsec to kiloparsec scales and will critically constrain future stellar-dynamical models of M87.

Unified Astronomy Thesaurus concepts: [AGN host galaxies \(2017\)](#); [Elliptical galaxies \(456\)](#); [Galaxy kinematics \(602\)](#); [High angular resolution \(2167\)](#); [Near infrared astronomy \(1093\)](#); [Supermassive black holes \(1663\)](#)

1. Introduction

Supermassive black holes (SMBHs) are believed to play a significant role in galaxy growth and evolution. This has been established on the basis of several relations between the SMBH mass (M_{BH}) and large-scale properties of the host galaxy, such as the bulge luminosity and stellar velocity dispersion (J. Kormendy & L. C. Ho 2013; N. J. McConnell & C.-P. Ma 2013; R. P. Saglia et al. 2016). The relations have further broad, far-reaching implications. They inform models of BH feeding and feedback (J. Silk & M. J. Rees 1998; A. C. Fabian 1999; F. Shankar et al. 2009), set the SMBH mass function important for making gravitational-wave estimates for Pulsar Timing Arrays and space-based detectors (G. Agazie et al. 2023; C. Matt et al. 2023; E. R. Liepold & C.-P. Ma 2024), serve as a reference to which reverberation-mapped active galactic nuclei (AGN) are compared to determine the virial coefficient needed to estimate M_{BH} from single-epoch spectra (A. E. Reines et al. 2013; J. E. Greene et al. 2024), and form the baseline when searching for possible redshift evolution (V. N. Bennert et al. 2011; F. Pacucci et al. 2023; Y. Zhang et al. 2023).

However, the low- ($M_{\text{BH}} \lesssim 10^6 M_{\odot}$) and high- ($M_{\text{BH}} \gtrsim 10^9 M_{\odot}$) mass ends of the SMBH–host galaxy relations are not well understood. Also, the relations are not as simple as once

thought, as galaxies with different structural properties and evolutionary histories—including brightest cluster galaxies, massive cored elliptical galaxies, compact early-type galaxies, and low-mass spiral galaxies—show surprises in the scaling relations (e.g., J. E. Greene et al. 2010; N. J. McConnell et al. 2011; A. C. Seth et al. 2014; J. L. Walsh et al. 2016; S. de Nicola et al. 2024; E. R. Liepold et al. 2025). Hence, more, robust M_{BH} measurements are needed at the low and high ends of the SMBH mass distribution and in a wide range of galaxy types.

The giant elliptical galaxy M87, with a $5.37 \times 10^9 M_{\odot}$ SMBH from stellar dynamics (E. R. Liepold et al. 2023), is a crucial anchor for the upper end of the scaling relations. The SMBH is one of the best studied in the local Universe, alongside Sagittarius (Sgr) A* in the Galactic Center, at the extreme opposite end of the SMBH mass distribution. Similar to Sgr A*, the increase in angular resolution over the years, culminating in the impressive Event Horizon Telescope (EHT) image of the SMBH shadow (Event Horizon Telescope Collaboration et al. 2019), is now paving the way for a deeper understanding of the compact object in M87 and the immediate surrounding environment. In addition to the EHT measurement, M87 has been the subject of numerous M_{BH} measurements over the past ~ 45 yr. While the data and modeling methods have improved, the stellar- and gas-dynamical M_{BH} determinations disagree by a factor of about 2 (e.g., R. J. Harms et al. 1994; F. Macchetto et al. 1997; K. Gebhardt et al. 2011; J. L. Walsh et al. 2013; E. R. Liepold et al. 2023).

The stellar-dynamical M_{BH} measurements for M87, in particular, have progressed from isotropic to anisotropic models, from Jeans models to orbit-based implementations, from sampling two-integral distribution functions to three integrals of motion, from modeling the SMBH and stars to additionally incorporating dark matter, and most recently from axisymmetric models to allowing for a triaxial intrinsic galaxy shape (e.g., W. L. W. Sargent et al. 1978; P. J. Young et al. 1978; A. Dressler & D. O. Richstone 1990; R. P. van der Marel 1994; J. Magorrian et al. 1998; K. Gebhardt & J. Thomas 2009; E. R. Liepold et al. 2023). Many of these models have been fit to observations of M87’s stellar kinematics from seeing-limited ground-based telescopes and on large spatial scales.

In contrast, obtaining high-angular-resolution stellar kinematics at M87’s nucleus has been challenging, due to the galaxy’s surface brightness core. It is difficult to acquire the high signal-to-noise (S/N) ratio observations needed to securely measure the detailed shape of the stellar line-of-sight velocity distribution (LOSVD) in M87’s faint galaxy center. The recent Keck Cosmic Web Imager (KCWI) study (E. R. Liepold et al. 2023) provided stellar kinematic measurements from a radius of $\sim 150''$ down to $\sim 1''$ from the center of M87, well within the SMBH’s gravitational sphere of influence ($\sim 5''$). For the innermost $\sim 1''$ of M87, only two high-angular-resolution stellar kinematic studies have been conducted—K. Gebhardt et al. (2011) collected adaptive optics (AO) observations from Gemini North’s Near-infrared Integral Field Spectrograph (NIFS), and D. A. Simon et al. (2024) presented AO Very Large Telescope (VLT) narrow-field-mode (NFM) Multi Unit Spectroscopic Explorer (MUSE) data (originally acquired by J. Osorno et al. 2023).

With the James Webb Space Telescope (JWST), we are now positioned to improve upon the limited number of small-scale stellar kinematic studies and probe the innermost region of M87 in unprecedented detail, thanks to JWST’s high angular resolution, reduced background, and enhanced sensitivity. Using JWST’s Near Infrared Spectrograph (NIRSpec) in integral field unit (IFU) mode, we acquire a new view of the stellar kinematics deep within the gravitational influence of the SMBH. We present these stellar kinematics and lessons learned after significant testing of the process used to extract the stellar kinematics. The NIRSpec stellar kinematics, combined with the recently published widefield IFU stellar kinematics of M87 (E. R. Liepold et al. 2023) and state-of-the-art dynamical models (e.g., E. Vasiliev & M. Valluri 2020; B. Neureiter et al. 2021; M. E. Quenneville et al. 2021, 2022; B. Tahmasebzadeh et al. 2022), will firmly establish M87 as a benchmark galaxy anchoring the upper end of the SMBH–galaxy scaling relations.

This paper is structured as follows. Section 2 presents the NIRSpec observations and data reduction, including modifications we made to the default data reduction pipeline. Section 3 describes our final data cube for M87. Sections 4 and 5 discuss the processes of spatial masking and binning and measuring the stellar kinematics, along with the steps we take to assess the robustness of the extracted kinematics. Finally, we place our results in the context of past work in Section 6 and conclude in Section 7. Throughout the paper, we assume a distance of 16.8 Mpc (adopted by EHT Collaboration et al. 2019; E. R. Liepold et al. 2023), such that $1''$ corresponds to

81.1 pc. All wavelengths are observed and are in vacuum, unless otherwise noted.

2. NIRSpec Observations and Data Reduction

We observed M87 using the JWST NIRSpec IFU with the G235H grating and the F170LP filter on 2023 May 31 as part of Cycle 1 GO-2228. We used the NRSIRS2 readout mode and integrated for a total of 6.6 hr on source, using 20 groups, 1 integration, and 16 exposures dithered with the small ($0''.25$ extent) cycle pattern to improve sampling of the point-spread function (PSF). We also obtained a LeakCal exposure at the first dither position.

The raw data were generated using the JWST Science Data Processing version 2023_2a, and we used the Calibration Reference Data System version 11.17.3, along with the context file `jwst_1140.pmap`. The version of the JWST Science Calibration Pipeline used to process the data was 1.11.4.

During Stage 1 (`calwebb_detector1`) of the pipeline, we perform detector-level corrections, like initializing the data-quality (DQ) array, checking for saturation, superbias, and reference pixel subtraction, correcting for nonlinearity, and removing the dark current. This stage also flags any large jumps between two consecutive groups relative to other consecutive pairs of groups. We further turn snowball flagging on, to correct for large cosmic-ray impacts; this setting is now on as the default for newer versions of the pipeline. The mean count rate for each pixel is determined by a ramp fitting step, and ultimately a 2D count-rate image for each exposure is produced. At this point, we also explored using an external package, NSClean (B. J. Rauscher 2024), to correct for correlated read noise. However, we found for our data of M87, read out with NRSIRS2, this correction was unnecessary, so we did not implement such a step. In newer versions of the pipeline, correcting for correlated read noise is built-in, as an optional step only, and can be implemented in Stage 2.

Next, in Stage 2 (`calwebb_spec2`), we assign the World Coordinate System information to the data, thus mapping detector pixels to sky and wavelength coordinates. We subtract the LeakCal exposure, previously processed through Stage 1 of the pipeline, from each M87 exposure, to remove the imprint from the NIRSpec Micro-Shutter Assembly (MSA). We further flag regions that were affected by MSA failed open shutters, apply a flat-field correction, correct for signal loss due to aperture and optical system effects, and complete the photometric calibration. The resulting products are calibrated exposures with units of MJy sr^{-1} .

Finally, Stage 3 (`calwebb_spec3`) of the pipeline identifies outliers that were not flagged in Stage 1 and generates a combined data cube of all calibrated exposures. However, we found that we could improve both of these steps, and we detail the changes we made relative to the default pipeline below.

2.1. Removing Additional Outliers

We complement the outlier detection step in Stage 3 of the pipeline by manually flagging any remaining bad pixels and artifacts in each of the exposures and adjusting the DQ array to “DO_NOT_USE” before assembling the data cube. With many dithered exposures, bad pixels in a single exposure can be ignored when constructing the final cube. Along similar lines, others have flagged and sometimes corrected bad pixels in the

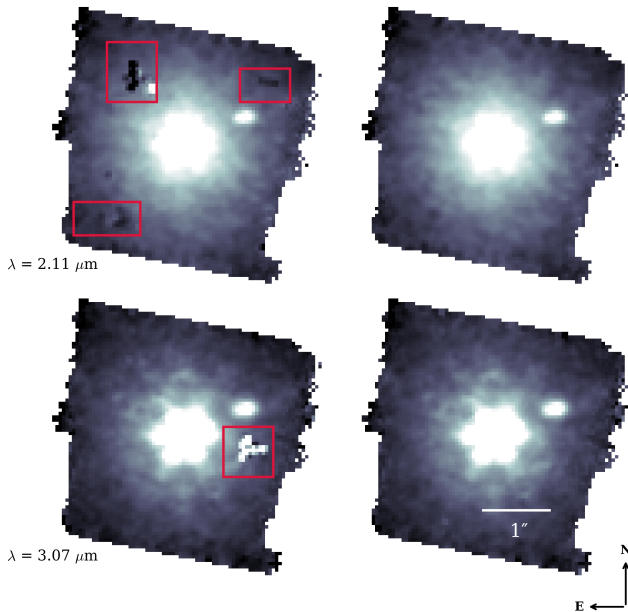


Figure 1. Images of M87 taken at two slices of the data cube when no additional bad pixels are flagged in the 2D detector images before building the cube (left) and the same two slices of the cube after applying our supplemental masking of bad pixels in each of the calibrated detector images prior to assembling the data cube (right). The red boxes in the left images denote positive and negative artifacts that remain in the final cube, but they do not appear in the data cube on the right when using our approach. The wavelength of each slice is given at the bottom of the left images, the spaxels are $0''.05$ on a side, and the images are oriented with north up. The feature to the northwest of the M87 nucleus is a jet knot.

2D detector images (e.g., M. Perna et al. 2023; M. Bianchin et al. 2024; T. A. Hutchison et al. 2024; B. Tahmasebzadeh et al. 2025). Another approach is to identify artifacts in the final 3D data cube (e.g., M. Perna et al. 2023; T. Bohn et al. 2024), but flagging bad pixels in each of the 2D calibrated detector images is preferable, because any artifacts in the detector image will be spread out and made worse by the interpolation during the cube-building process.

As an example, in the left set of images in Figure 1, we show two slices of the final M87 data cube when the DQ array is not adjusted and additional bad pixels (beyond those caught by the JWST pipeline, even with snowball detection turned on) are not flagged. There are many extended, irregularly shaped negative and positive artifacts in the data cube, and this occurs across all wavelengths. In contrast, the right set of images in Figure 1 displays the same two slices of the final data cube when we mask any remaining bad pixels in the 2D detector image for each exposure before building the combined cube. For this figure, all parts of the data reduction are the same, with the exception of whether the supplemental bad pixels that we identified are masked in the 2D detector images before generating the data cube. As can be seen, there is a substantial improvement in our final data cube.

2.2. Building a Data Cube

We further make an adjustment in how the exposures are merged when building the combined data cube, to mitigate artifacts near the detector gap. Other analyses (e.g., D. Wylezalek et al. 2022; Y. Ishikawa et al. 2025) have also elected to modify the standard procedure for producing a merged data cube, and in some cases (J.-B. Ruffio et al. 2024) a

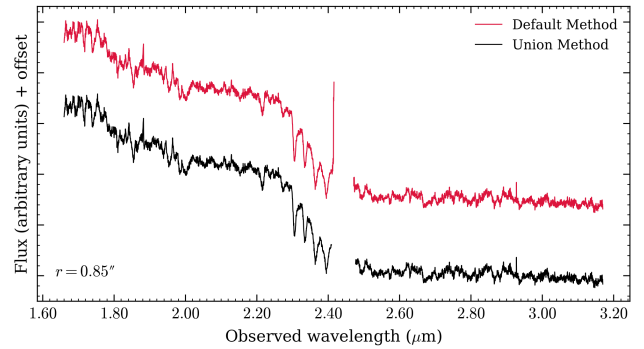


Figure 2. A comparison of the spectra extracted from a single $0''.05$ spaxel in the final M87 data cube when using the standard method (red) and our union method (black) for building the cube. With the typical approach, artifacts are commonly seen adjacent to the NRS1/NRS2 detector gap. The detector gap is the white space with missing data, at $\sim 2.45 \mu\text{m}$ above. With the union method, the spectra are clean and enable the secure measurement of the stellar LOSVD from the CO bandheads near the detector gap.

data cube is not even created. In our case, we generate our final data cube by first using the pipeline’s cube-building step, inputting the calibrated detector images from the 16 dithered exposures, requiring the spaxels to be $0''.05$ on a side, and keeping the other default settings. This allows us to determine the dimensions of an output cube and the R.A. and decl. of the center.

We then construct individual cubes for each exposure, again using the pipeline’s cube-building step, but we require each exposure be drizzled onto the common 3D grid that was previously determined. We also make a minor alteration to the pipeline’s cube-building code, so that the drizzle weights of the voxels in the individual cubes are stored. We combine the 16 individual cubes together and perform additional masking, requiring all voxels to have a DQ flag of “GOOD,” a positive drizzle weight, and an intensity that is finite. Nonsatisfying voxels are masked during the merger, by designating their intensity to be NaN and their drizzle weight to be 0. Furthermore, for each spaxel in each individual cube, we identify the apparent boundaries of the gap between the NRS1 and NRS2 detectors, by locating the longest contiguous region of spectral pixels with NaN values and 0 drizzle weights. The union of these regions across the 16 dithered exposures is determined for each spaxel and masked when building the final cube, again by designating the intensity to be NaN and the summed drizzled weight to be 0. We note that because the individual cubes have a common grid and the drizzle weights from the pipeline’s cube-building step are stored, no additional interpolation step is needed when the individual cubes are merged together.

With our union method for assembling the data cube, the final cube has minimal artifacts in the spectral region near the detector gap, and many fewer spaxels, particularly at the spatial edges of the cube, contain large amounts of NaN values. Eliminating artifacts by the detector gap is especially important, as in Section 5 we measure the detailed shape of the stellar LOSVD from the CO bandheads in this spectral region. Figure 2 demonstrates the spurious features that can appear around the detector gap when we use the typical procedure. For comparison, we plot the spectrum from the same spaxel in our final cube when adopting our union method. For this figure, all aspects of the data reduction process are identical, including the additional masking of bad pixels in 2D detector

images, and the only difference is in how the merged data cube is constructed.

While one could spectrally mask anomalies near the detector gap as a postprocessing step when measuring the stellar kinematics, we find that the artifacts are unpredictable, occurring at varying spectral locations away from the detector gap and impacting the CO bandheads differently across the NIRSpec field of view (FOV). Our tests using the default method for assembling the final data cube and applying a spectral mask to exclude the artifacts near the detector gap when fitting the spectra revealed that the width of the spectral mask had an impact on the inferred stellar LOSVDs for M87. Instead, our union method for building the final cube yields clean spectra, removes the need for spectral masking near the detector gap, and results in robust stellar kinematic measurements.

3. The M87 Data Cube

After completing the data reduction, including implementing all of the changes to the default pipeline described in Sections 2, 2.1, and 2.2, our final cube covers the central $3'' \times 3''$ region of M87 with high angular resolution and a sampling of $0''.05 \text{ pixel}^{-1}$ along the spatial x - and y -axes. The wavelength axis spans $1.66\text{--}3.17 \mu\text{m}$, with a scale of $3.96 \times 10^{-4} \mu\text{m pixel}^{-1}$ and a spectral resolving power of $R \sim 2700$. In the top panel of Figure 3, we compare a spectrum extracted from a single $0''.05$ spaxel from the cube generated with the default JWST pipeline and the same spaxel from our final data cube. While Figures 1 and 2 focused on isolating specific modifications made to the standard reduction, the top panel of Figure 3 compares the outcome when the default JWST pipeline is run from start to finish versus when all of our changes are implemented together.

The NIRSpec data have spectacular S/N ratios, even in individual spaxels near the nucleus and at the edge of the data cube, with values typically of ~ 150 (see Section 5). The K -band CO bandhead absorption features are prominent throughout the FOV, and given M87's redshift, we find between two and four of the ^{12}CO bandheads blueward of the detector gap, as the spectral location of the gap varies across the FOV. These K -band CO bandheads serve as the primary tracer for measuring the stellar kinematics. We also find numerous emission lines, which previously have gone undetected in the near-infrared (e.g., K. Gebhardt et al. 2011), highlighting the sensitivity of JWST and the benefits of space-based observations. The emission features we detect include multiple warm molecular hydrogen (H_2) lines,⁵ as well as a few hydrogen recombination lines,⁶ the strongest of which is $\text{Pa}\alpha$. The middle panel of Figure 3 presents spectra from single spaxels and illustrates the high S/N ratio and the absorption and emission lines present. In addition to the emission lines labeled in Figure 3, at other spatial locations we also detect $\text{H}_2(3\text{--}2)\text{S}(7)$, $\text{H}_2(1\text{--}0)\text{S}(0)$, $\text{H}_2(1\text{--}0)\text{Q}(5)$, and $\text{H}_2(1\text{--}0)\text{O}(4)$. An analysis of the gas kinematics will be the subject of future work.

3.1. Wiggles in the Nuclear Spectra

Although the M87 data have high S/N ratios and strong absorption and emission lines, the spectra at the nucleus show

unphysical periodic amplitude modulations. These ‘‘wiggles’’ appear as a result of the undersampling of the PSF and are discussed at length by D. R. Law et al. (2023). While D. R. Law et al. (2023) demonstrate that a four-point dither pattern reduces the undersampling artifacts, we see that even with our 16-exposure small-cycling dither pattern, the wiggles remain. Likewise, J.-B. Ruffio et al. (2024) find that a nine-point dither pattern did not result in as significant an improvement in the wiggles as desired, and they further discuss how the effectiveness of the dither pattern is field- and wavelength-dependent. Beyond increasing the number of dithers, perhaps the preset dither pattern itself can be reexamined and refined. In some cases, the exponential modified Shepard method (EMSM) is used when generating the data cube, in order to reduce the wiggles (M. A. Marshall et al. 2023; M. Perna et al. 2023). However, EMSM data cubes have slightly lower spatial and spectral resolution relative to the drizzled versions (D. R. Law et al. 2023), and thus we continue to use drizzle weighting.

In the bottom panel of Figure 3, we show representative spectra from single spaxels at increasing projected radii, r , from the nucleus. The wiggles become less problematic with increasing r and are no longer an issue by $r \sim 0''.45$. While several packages have been released, outside of the JWST pipeline, to correct the wiggles (M. Perna et al. 2023; A. Dumont et al. 2025; A. J. Shajib 2025), and we have experimented with our own procedures, we find the extracted stellar kinematics for M87 to be sensitive to the exact methods adopted. Moreover, the impact of the AGN can be seen in the innermost spectra, specifically in the dilution of the CO bandheads and the shape of the continuum, but the AGN is no longer an issue by $r \sim 0''.45$. For these reasons, we choose to focus on the spectra at $r \geq 0''.45$ in this paper. Investigation of the innermost region of the data will be the subject of future work.

4. Spatial Masking and Binning

Given the wiggles and the impact of the AGN on the spectra at the nucleus, we apply a circular mask with $r < 0''.45$ that is centered on the spaxel with the largest intensity when summing over the wavelength axis of the data cube. We mask the jet knot to the northwest of the nucleus, based on visual inspection of the collapsed data cube and the presence of possible wiggles in the spectra at the location of the jet knot. The outermost edges of the data cube are also masked, such that there are no NaN values for the intensity within the wavelength range over which we fit the stellar kinematics (see Section 5) and there is a single contiguous field of spaxels from which we measure the stellar LOSVDs.

We use the Voronoi binning method (M. Cappellari & Y. Copin 2003) to construct spatial bins and ensure all the spectra have the necessary high S/N ratio to reliably measure the stellar kinematics. Because we have very high S/N ratios in single spaxels over much of the FOV, when applying the Voronoi binning method, only the outer regions are binned and the bin sizes remain fairly small. After a round of Voronoi binning, we adjust the edges of the spatial mask to exclude bins that still do not meet our bin S/N ratio threshold of 115 and smooth the irregularly shaped edges of the updated mask. The Voronoi binning is repeated, ultimately resulting in 2810 bins, of which 2232 are composed of a single spaxel.

⁵ <https://www.gemini.edu/observing/resources/near-ir-resources/spectroscopy/important-h2-lines>

⁶ <https://www.gemini.edu/observing/resources/near-ir-resources/spectroscopy/hydrogen-recombination-lines>

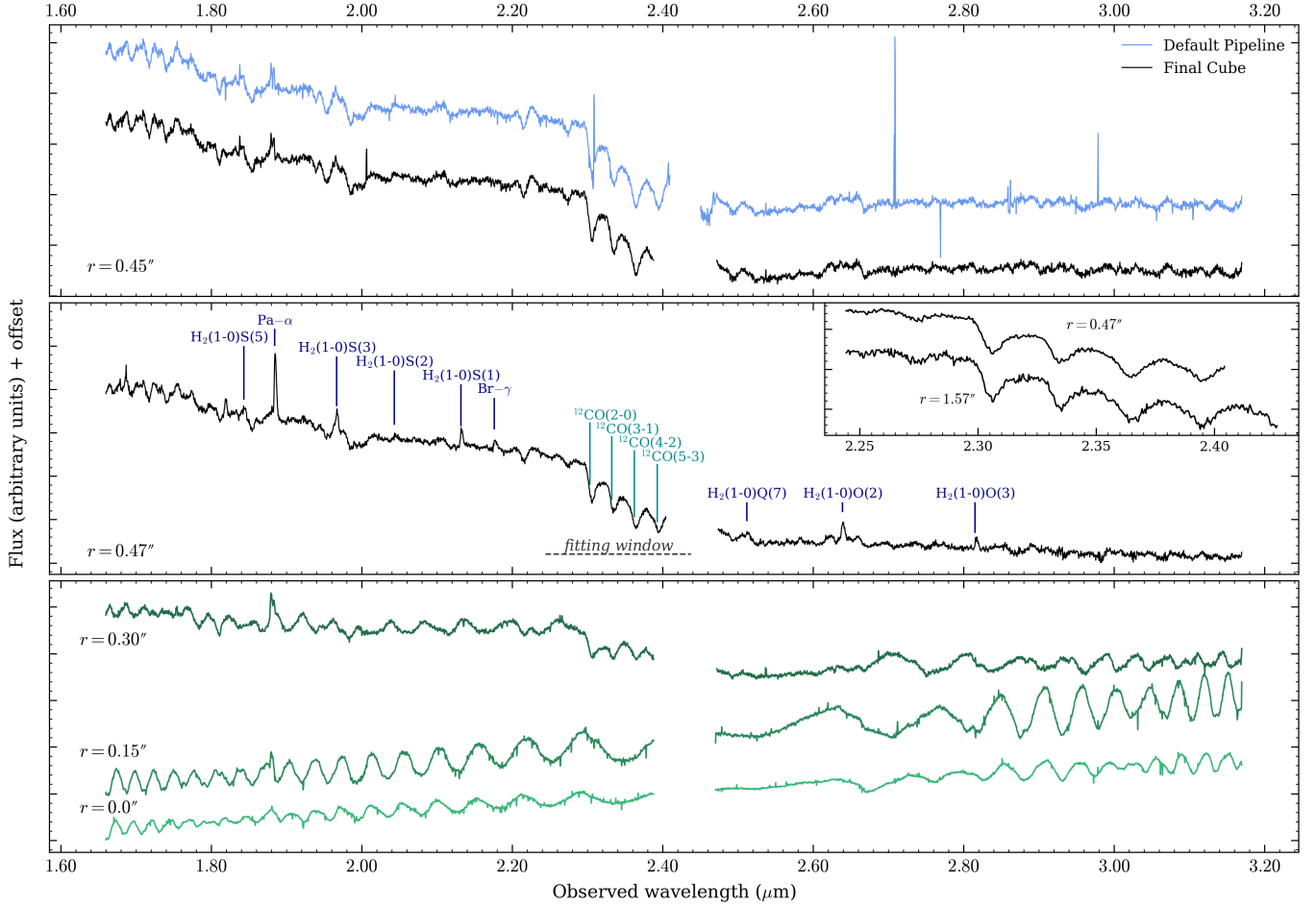


Figure 3. Top: spectra from a single 0.05 spaxel in the M87 data cube constructed using the default JWST pipeline (light blue) and from one in the final data cube generated using the modifications to the pipeline described in Sections 2, 2.1, and 2.2 (black). The latter spectrum exhibits noticeable improvements relative to the former. Middle: an example spectrum from our final data cube, extracted from a single 0.05 spaxel just outside the nucleus, with the emission lines labeled in dark blue and the ^{12}CO bandhead absorption features labeled in teal. The horizontal dashed gray line indicates the wavelength range over which the CO bandheads are fit, as described in Section 5. A zoom-in of this spectral region for the same spectrum is shown in the top right inset of the panel, along with a second spectrum extracted from a single spaxel near the edge of the data cube. Even in single spaxels, just outside the nucleus and at the edge of the FOV, the S/N ratio is very high. Bottom: typical nuclear spectra from single spaxels in the final M87 data cube. Wiggles are clearly seen, despite our 16-exposure small-cycling dither pattern. The wiggles improve with increasing distance from the center and are no longer observed in the top two panels, at $r \sim 0.45$.

5. Stellar Kinematics

We use the penalized pixel-fitting method (pPXF; M. Cappellari 2023, version 9.4.2) to compare velocity template stars from the PHOENIX synthetic library (T.-O. Husser et al. 2013), convolved with an LOSVD and adjusted by a degree 3 multiplicative Legendre polynomial, to the observed galaxy spectrum in each spatial bin. The LOSVD is parameterized in terms of a Gauss–Hermite (GH) series, and we report the radial velocity V , velocity dispersion σ , and higher-order GH moments ($h_3 - h_8$), which quantify the asymmetric and symmetric deviations of the LOSVD from Gaussian. We fit over a wavelength range focused on the CO bandheads located on the NRS1 detector and spectrally mask the Ca I absorption at a rest wavelength of $2.26 \mu\text{m}$ that is not well matched by our PHOENIX template library. The details of the template library, the masking of Ca I, the wavelength range we fit over, and other spectral fitting parameters are discussed in Section 5.1 below.

For every spatial bin, after an initial fit to the observed M87 spectrum with a pPXF bias parameter of 0.2, we determine the

uncertainties on the stellar kinematics using a Monte Carlo procedure. During each of the 200 Monte Carlo realizations, we add random Gaussian noise to the initial best-fit pPXF model, such that the noise is equal to the standard deviation of the model residuals. We refit with pPXF with the bias turned off and record the stellar kinematics from each realization. With the 200 iterations complete, we calculate the median and standard deviation of the resulting distribution for each GH moment, which we take to be the kinematic values that we report throughout the paper and their 1σ uncertainties.

Figure 4 shows the maps of the first eight GH moments. We do not symmetrize the maps to remove overall offsets in the odd-GH moments and average away outliers, as is common practice prior to dynamical modeling (e.g., J. L. Walsh et al. 2015; C. A. Roberts et al. 2021; S. Thater et al. 2022). However, we do subtract offsets in the odd-GH moments, and the offsets are determined by calculating the median value over all spatial bins. For V , this offset corresponds to the galaxy’s systemic velocity, and for the higher odd moments, the offsets are typically attributed to template mismatch (e.g., K. Mehrgan et al. 2023). We find very small offsets for

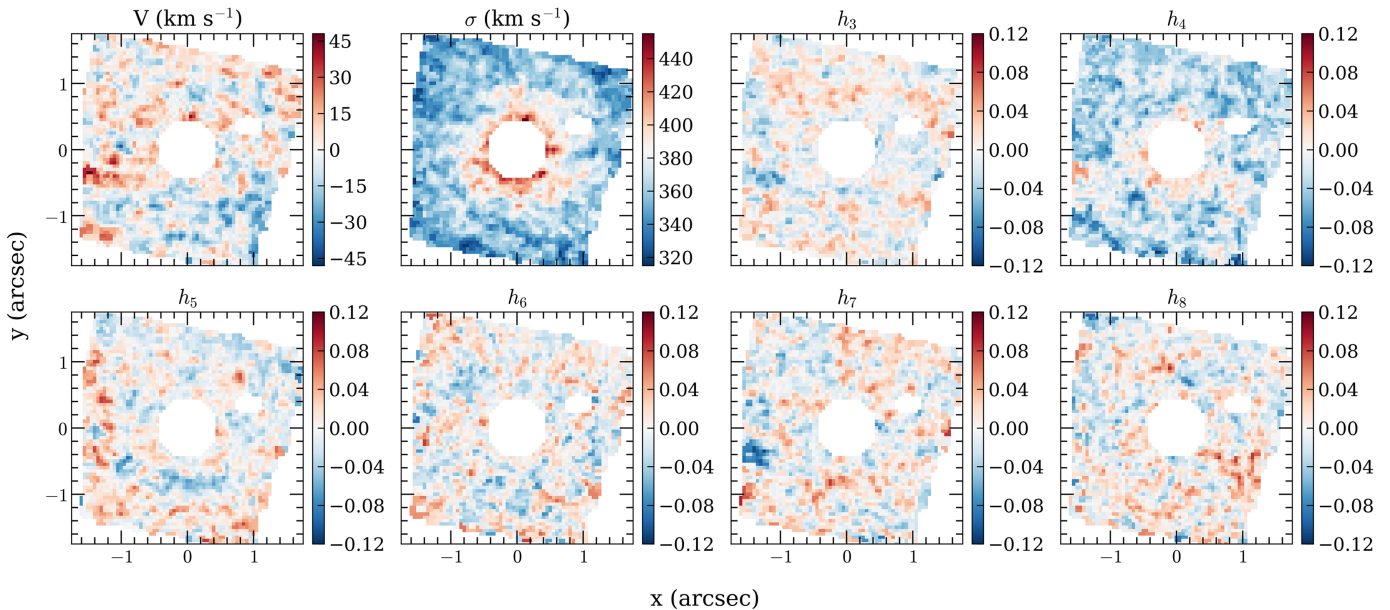


Figure 4. The first eight GH moments used to describe the LOSVD are shown across the NIRSpc FOV. There are 2810 spatial bins for which a kinematic measurement was made, and 2232 of the spatial bins are composed of a single $0''.05$ spaxel. The central $0''.45$ and the jet knot to the northeast have been masked. The maps are oriented with north up and east to the left.

h_3 , h_5 , and h_7 , of -0.002 to -0.006 , indicating minimal template mismatch.

From the maps, we find velocities of $V \sim \pm 45 \text{ km s}^{-1}$, with generally positive velocities to the northeast and negative velocities to the southwest of the nucleus, although there is not very clear coherent rotation. These broadly positive velocities to the northeast and negative velocities to the southwest match up with a clearer rotational signature seen in the inner ($15'' \times 15''$) part of the large-scale KCWI data (E. R. Liepold et al. 2023). In addition, from the NIRSpc data, we see that the velocity dispersion sharply rises toward the center, reaching $\sim 420 \text{ km s}^{-1}$ at $r = 0''.45$; there is a slight elevation in h_4 toward the nucleus; and the other higher GH moments fluctuate about zero. Representative uncertainties are 5 km s^{-1} and 7 km s^{-1} for V and σ , respectively, and 0.01 – 0.02 for $h_3 - h_8$. The S/N ratio, taken to be the median of the M87 spectrum over the common wavelength range fit among all the spatial bins (of 2.2443 – $2.3632 \mu\text{m}$) divided by the standard deviation of the pPXF residuals, spans $S/N = 116$ – 223 , with a median value of 166. Example spectral fits at different spatial locations can be found in panel (d) of Figure 5 (the top spectrum) and in panels (a)–(c) in Figure 6.

5.1. Robustness of the Stellar Kinematics

We examine the robustness of the fiducial stellar kinematics and provide details about these tests below.

5.1.1. Template Libraries and Spectral Masking of Ca I

For the fiducial kinematic measurement, we select 90 stars from the high-resolution PHOENIX library (T.-O. Husser et al. 2013), with effective temperatures of $T_{\text{eff}} = 2400$ – 6500 K , surface gravities of $\log(g) = 0$ – 5 , metallicities of $-0.5 \leq [\text{Fe}/\text{H}] \leq +0.5 \text{ dex}$, and solar alpha element abundances. The chosen properties are representative of G, K, and M giant, supergiant, and dwarf stars with a range in metallicity. The PHOENIX library is commonly used to

analyze the kinematics in nearby galaxies observed with JWST (A. Dumont et al. 2025; D. D. Nguyen et al. 2025; B. Tahmasebzadeh et al. 2025; M. A. Taylor et al. 2025), because it spans a wide wavelength range at high spectral resolution and many stars with a variety of properties can be sampled. However, the synthetic spectra assume a particular stellar atmospheric code. Although empirical template libraries are more limited in wavelength coverage, S/N ratios, and numbers of stars, comparing results from synthetic and empirical libraries is essential, especially because using empirical templates has been the standard practice for pre-JWST kinematic measurements.

In addition, when using the PHOENIX library, we observe that the Ca I absorption in M87 is not matched well, and thus we mask the line. D. Krajnović et al. (2009) note that properly fitting Ca I requires cool dwarf stars. While our PHOENIX library does include such stars, we still do not find a good match to the feature. Other work using empirical template libraries lacking cool dwarf stars also had difficulty fitting Ca I and chose to mask the line (e.g., J. L. Walsh et al. 2016, 2017).

Given that PHOENIX is a synthetic library and the M87 Ca I feature is not fit well, we explore other empirical template libraries, including a set of stars we observed with the OH-Suppressing Infrared Integral Field Spectrograph (OSIRIS) aided by AO when the instrument was on the Keck II telescope, which we will refer to as the K2 OSIRIS library, and the C. Winge et al. (2009) Gemini Near-Infrared Spectrograph (GNIRS) library. The K2 OSIRIS library (J. L. Walsh et al. 2012) is composed of 22 K and M giant stars and G and K dwarf stars observed with the broadband K filter over 1.97 – $2.38 \mu\text{m}$ with $R \sim 3800$. The Winge GNIRS library contains 23 G, K, and M giant, supergiant, and dwarf stars observed with GNIRS in IFU mode over both blue and red spectral setups, covering 2.15 – $2.43 \mu\text{m}$ (in air) at $R \sim 7600$. As part of the data reduction, C. Winge et al. (2009) fit the continuum shape of each template star and removed it. Thus, we find a slightly larger multiplicative polynomial degree of 4

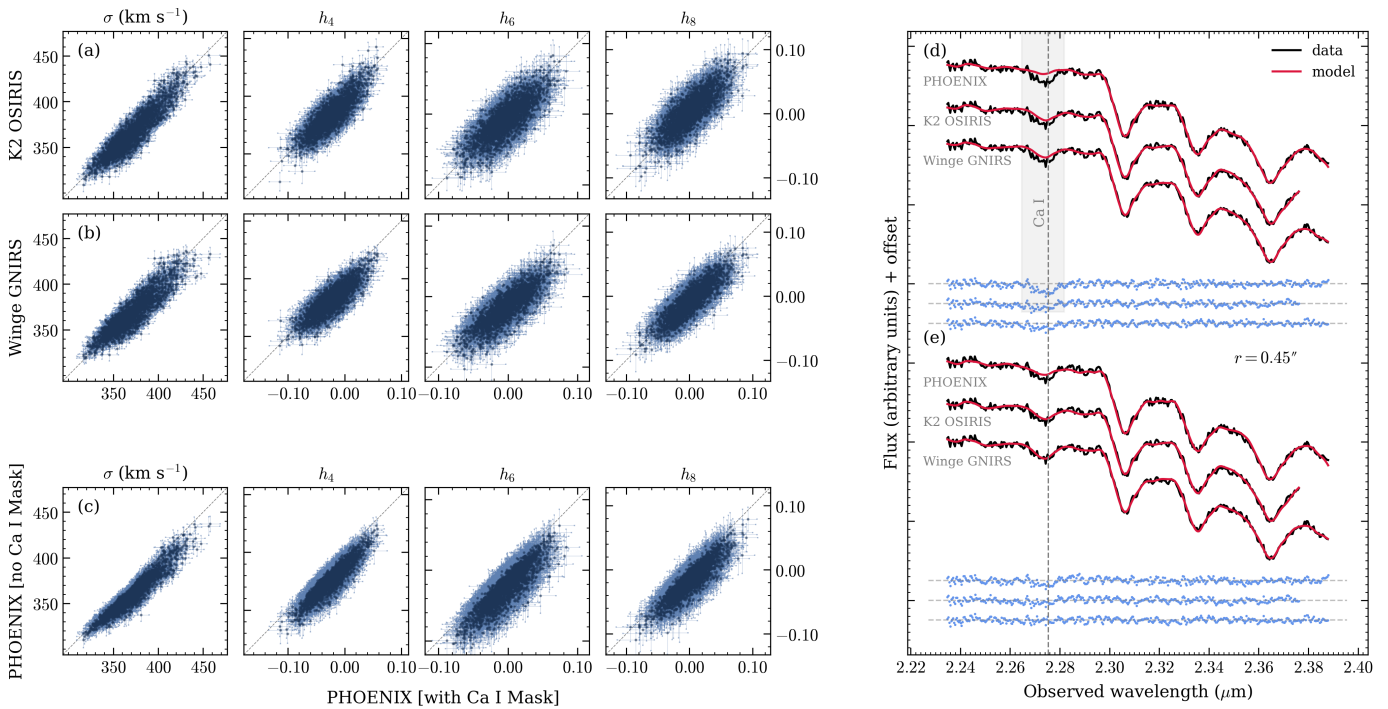


Figure 5. Left: panels (a) and (b) compare even-GH moments derived using the K2 OSIRIS and Wingé GNIRS libraries to those from the PHOENIX library, all with Ca I masked. Panel (c) contrasts moments obtained with and without masking Ca I, using PHOENIX templates. The dotted line indicates the one-to-one correspondence. When Ca I is masked, the GH moments are consistent across all libraries. However, omitting the mask with PHOENIX introduces a systematic offset in the kinematics. Although not shown, when using K2 OSIRIS and Wingé GNIRS, consistent kinematics are found regardless of whether Ca I is masked. Right: panels (d) and (e) show spectral fits to the same M87 spectrum (black), using PHOENIX, K2 OSIRIS, and Wingé GNIRS templates, with Ca I masked (gray band) and unmasked, respectively. The red lines show the best-fit pPXF models, with the residuals in blue. All models are a good match to the data when Ca I is masked. When Ca I is not masked, the PHOENIX templates cannot reproduce Ca I well, whereas the two empirical libraries are able to do so. While the same single-spaxel M87 spectrum is shown, the ending wavelengths differ, due to the varying spectral coverage of the template libraries, with K2 OSIRIS cutting off earlier than the others.

is needed when using the Wingé GNIRS library to match the M87 NIRSspec data compared to when using the PHOENIX and K2 OSIRIS libraries, both of which have template spectra with the continuum shape intact.

When fitting the M87 NIRSspec data in the same manner as described in Section 5, including masking Ca I but adopting the K2 OSIRIS template library, we recover consistent kinematics, as shown in panel (a) of Figure 5. Likewise, using the Wingé GNIRS library, continuing to mask Ca I in the M87 data, and using a multiplicative polynomial of degree 4 yield comparable stellar kinematics as the fiducial run, as can be seen in panel (b) of Figure 5. While Figure 5 displays only the even moments, we see similar results for the odd moments. For example, the distribution of V differences (V extracted using K2 OSIRIS $- V$ determined with PHOENIX, both with Ca I masked) over all spatial bins ranges from $\pm 5 \text{ km s}^{-1}$ (the 68% interval). Spectral fits to the same M87 spectrum but using the three template libraries are given in panel (d) of Figure 5. The best-fit pPXF model reproduces the observed M87 spectrum nicely over the wavelengths fit. The masked Ca I line is not matched when using the PHOENIX library (top spectrum of panel (d)) and is better recovered when using the K2 OSIRIS and Wingé GNIRS libraries (middle and bottom spectra of panel (d)), even though the data in this spectral region are not part of the fit.

Next, we repeat the measurement with the three template libraries but do not mask Ca I. With both the K2 OSIRIS and Wingé GNIRS libraries, the stellar kinematics are identical, regardless of whether Ca I is masked or included in the fit,

although there is a clear offset in the even-GH moments when the PHOENIX library is used and the Ca I is masked or not masked (panel (c) of Figure 5)—the even-GH moments are systematically biased low when Ca I is not masked. More specifically, the distribution of velocity dispersion differences (σ extracted when Ca I is not masked $- \sigma$ recovered with the fiducial settings) over all spatial bins is systematically shifted and skewed, ranging from -17 km s^{-1} to -5 km s^{-1} (the 68% interval), with a median difference of -9 km s^{-1} . The differences become worse at high dispersions and span from -25 km s^{-1} to -6 km s^{-1} (68% interval), with a median of -16 km s^{-1} for bins with a fiducial $\sigma > 400 \text{ km s}^{-1}$. Both systematic shifts are outside the typical statistical uncertainty of $\sim 7 \text{ km s}^{-1}$ derived from the Monte Carlo simulation for σ in Section 5. Panel (e) of Figure 5 illustrates the same M87 spectrum as panel (d) and the best-fit pPXF model with the PHOENIX, K2 OSIRIS, and Wingé GNIRS libraries when Ca I is not masked. Again, Ca I is poorly fit by the PHOENIX library, while the two empirical libraries are capable of matching Ca I and can do so even better than in panel (d), now that this spectral region is part of the fit.

Since both empirical libraries reproduce the Ca I feature and yield consistent kinematics whether Ca I is masked or not, coupled with the stability in the kinematics regardless of the three template libraries (PHOENIX, K2 OSIRIS, Wingé GNIRS) adopted, as long as Ca I is masked, we conclude that using the PHOENIX library and masking Ca I produces robust stellar kinematics.

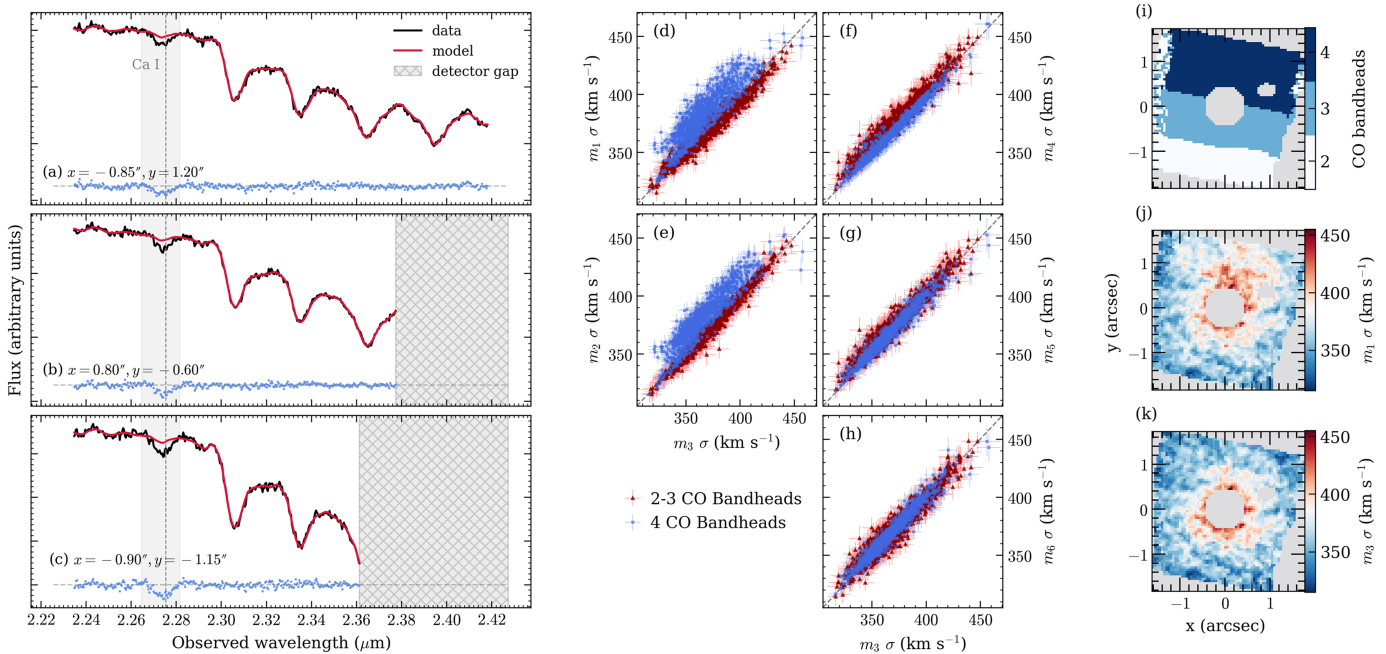


Figure 6. Left: panels (a)–(c) present example M87 spectra (black) from single spaxels at different spatial locations, best-fit pPXF models (red), and residuals (blue). The Ca I feature is masked (gray band). There are two to four CO bandheads within the fitting region, due to the spectral variation of the detector gap (hatched band). Middle: panels (d)–(h) compare velocity dispersions measured when using polynomial degrees 1–2 and 4–6 relative to degree 3. Measurements made from spectra with two or three CO bandheads (red points) follow the one-to-one line (the dashed black line) in panels (d)–(h), but measurements from spectra with four CO bandheads (blue points) only fall on the one-to-one line in panels (f)–(g). At least a degree 3 polynomial is needed for accurate fits over the broader wavelength range with four CO bandheads, whereas the results are consistent across degrees when fitting the narrower wavelength range with two or three bandheads. Right: panel (i) maps the number of CO bandheads on the NRS1 detector, and panels (j) and (k) show velocity dispersions when using degree 1 and degree 3 polynomials, respectively. Since the number of CO bandheads varies systematically across the FOV and using too low a polynomial order causes the dispersion to be overestimated when four CO bandheads are fit, there is an artificial gradient in the dispersion map in panel (j), but using a degree 3 polynomial resolves this issue. The same behavior is seen for the other even-GH moments.

5.1.2. Additive and Multiplicative Polynomials

Often additive polynomials are used to aid in modeling an AGN component or account for sky-subtraction errors, whereas multiplicative polynomials are employed to correct for small errors in spectral flux calibration (M. Cappellari 2023). In Section 5, we adopt a multiplicative Legendre polynomial of degree 3 to modify the shape of the LOSVD-convolved template stars. Although M87 harbors a low-luminosity AGN, our spectral fitting is restricted to the region outside the point source, at $r \geq 0''.45$, and we should not need an additive polynomial. For completeness, we conduct tests with an additive polynomial of degree 0 and 1, but these reveal elevated values for h_6 and h_8 of ~ 0.10 – 0.15 over the entire FOV that are not realistic. Hence, we continue without an additive polynomial.

When varying the multiplicative polynomial degree between 1 and 6, we recover consistent kinematics when there are two and three CO bandheads before the detector gap, but find we require a multiplicative polynomial with degree ≥ 3 when there are four bandheads before the detector gap. This behavior and its implications can be seen in Figure 6. As shown in panels (a)–(c) of Figure 6, since we use the same starting wavelength but differing ending wavelengths for the fit that go to the detector gap in each spatial bin, there are anywhere from two to four CO bandheads being fit and there are varying wavelength ranges over which the fit is performed.

Panels (d)–(h) of Figure 6 compare the dispersion measured when using degrees 1–2 (panels (d) and (e)) and 4–6 (panels (f)–(h)) to the value determined when using a degree 3

polynomial. The red points correspond to spectra with two and three CO bandheads, and in all panels (d)–(h), the red points fall along the one-to-one line. In other words, σ is stable and multiplicative degree 1–2 and 4–6 polynomials return similar dispersions as when a degree 3 polynomial is used. In contrast, the blue points correspond to spectra with four CO bandheads, and these dispersions in panels (d) and (e) are biased high, above the one-to-one line, but lie along the one-to-one line in panels (f)–(h). Therefore, when four bandheads and a wider wavelength range are fit using too low a multiplicative polynomial degree, we measure an inflated σ . Once a large enough polynomial degree is used, the dispersions are consistent and there is no dependence on the multiplicative polynomial degree.

Because the spectral location of the detector gap varies across the NIRSpc FOV, there is a spatial dependence on the number of CO bandheads being fit, as displayed in panel (i) of Figure 6. The southern portion of the IFU has spectra with two CO bandheads fit, and the northern part of the IFU has spectra with four CO bandheads fit. Consequently, when too low a multiplicative polynomial degree is adopted, as in panel (j) of Figure 6, there is a false gradient detected in σ , with enlarged dispersions in the northern part of the IFU where there are four CO bandheads present. With a degree 3 multiplicative polynomial, the spatial gradient in σ is eliminated (panel (k)) and the spatial trend in the dispersion, with the dispersion rising toward the nucleus, is real. While Figure 6 focuses on the velocity dispersion, we find the same is true for the other even-GH moments: h_4 , h_6 , and h_8 .

5.1.3. Spectral Fitting Window

As there are only one or two very weak CO bandheads seen at the start of the NRS2 detector, when running pPXF we fit over a wavelength range starting at $2.2347 \mu\text{m}$ and fit up to the detector gap. Such a fitting window has the benefit of targeting the NRS1 CO bandheads along with sufficient continuum, being free from prominent emission lines, and multiple velocity template libraries cover this spectral region. A similarly focused wavelength range was fit for other nearby galaxies observed with NIRSspec (D. D. Nguyen et al. 2025; B. Tahmasebzadeh et al. 2025; M. A. Taylor et al. 2025).

We adjust the starting wavelength, testing values of 2.2458 , 2.2605 , and $2.2855 \mu\text{m}$, and continue to fit to the detector gap for each spatial bin. In general, we find consistent results with the fiducial kinematics presented in Section 5, but there is a systematic deviation in the even moments when using a starting wavelength of $2.2855 \mu\text{m}$ relative to the fiducial kinematics in spatial bins with high velocity dispersions. For example, in bins with a fiducial $\sigma > 400 \text{ km s}^{-1}$, the difference (σ found with a fitting wavelength starting at $2.2855 \mu\text{m} - \sigma$ determined with the fiducial settings) ranges from -22 km s^{-1} to 1 km s^{-1} (the 68% interval), with a median of -11 km s^{-1} . In the case of using $2.2855 \mu\text{m}$ for the starting wavelength, the kinematics appear to be less stable, likely due to the limited and less-well-defined continuum before the start of the very broad $^{12}\text{CO}(2-1)$ bandheads in M87. Exploring wider wavelength ranges—such as fitting over the NRS1 detector or the entire NRS1+NRS2 wavelength range—requires a thorough examination of the most appropriate polynomial to use (see Section 5.1.2) and the spectral masking of emission lines. We do not include such a fit here.

5.1.4. Number of GH Moments

Many prior kinematic studies that describe the LOSVD with a GH series use four, or occasionally six, moments (e.g., K. A. Merrell et al. 2023; S. Thater et al. 2023), although given the high S/N ratio of the NIRSspec data, we report the first eight GH moments. Recent studies with high-S/N ratio spectra also utilize eight GH moments (J. D. Pilawa et al. 2022; E. R. Liepold et al. 2023, 2025; J. Pilawa et al. 2025), and K. Mehrgan et al. (2023) emphasize that nonparametrically derived LOSVDs observed for massive early-type galaxies require at least six or eight GH moments to capture the detailed structures of the distributions. E. R. Liepold et al. (2020) demonstrated for the massive early-type galaxy NGC 1453 that truncating the GH series early can result in inflated values for the last even moment measured and that continuing the series out to higher terms resolves the issue, as the additional higher even moments then scatter about 0.

We explore fitting 4–14 GH moments and find consistent results with the fiducial kinematics presented in Section 5 for the moments in common between the runs. Therefore, we do not here encounter a situation where the last even moment is elevated if the GH series is truncated at a low order. When fitting two GH moments and comparing to the fiducial kinematics, we find a slight systematic shift mainly at high dispersions. In spatial bins with a fiducial $\sigma > 400 \text{ km s}^{-1}$, the difference (σ when fitting two GH moments $- \sigma$ from the fiducial settings) ranges from -15 km s^{-1} to 0 km s^{-1} (the 68% interval), with a median of -6 km s^{-1} . We continue to

present the first eight GH moments, because the high-quality NIRSspec data enable such a measurement and the M87 large-scale stellar kinematics from Keck KCWI were extracted in the same way (E. R. Liepold et al. 2023). We will fit orbit-based triaxial dynamical models to both the NIRSspec small-scale and the KCWI widefield stellar kinematics in the future.

5.1.5. Relative Weights of the Template Stars

To derive our fiducial kinematics, we fit pPXF to each spatial bin separately, allowing the weights applied to the template stars to change between bins. Another approach is to require the relative weights of the template stars to remain fixed between spatial bins when measuring the kinematics. We carry out this second method and determine the relative template weights through an initial fit to a very-high-S/N ratio spectrum of M87, constructed by summing together all the M87 spectra within a central circular annulus with inner and outer radii of $0''.45$ and $0''.7$. The resulting optimal template is then used as the reference when comparing to the observed M87 spectrum in each spatial bin. We find kinematics that are consistent with our fiducial run.

5.1.6. Spectral Resolution

We assume the NIRSspec data have a constant R of 2700, or an instrumental dispersion of $\sigma_{\text{inst}} = 47 \text{ km s}^{-1}$, following the JWST User Documentation (JDox)⁷ for the G235H grating at our data cube’s central wavelength of $2.415 \mu\text{m}$. Recently, A. J. Shajib et al. (2025) found that the in-flight spectral resolution exceeded the JDox estimates by 5%–45% across all NIRSspec configurations and wavelengths. If instead during the pPXF fit we adopt $R = 3289$, calculated using A. J. Shajib et al. (2025) for the F170LP/G235H IFU configuration at a wavelength of $2.415 \mu\text{m}$, we obtain identical kinematics to the fiducial set in Section 5.

6. Multiscale Kinematic Comparison

We measure the stellar kinematics in the central region of M87, probing well within the SMBH sphere of influence and mapping the kinematics in exquisite detail. In this section, we place our results in context by comparing with previous multiscale stellar kinematic measurements of M87 obtained using ground-based facilities.

6.1. Large-scale Measurements

Since M87 has been the subject of numerous stellar-dynamical studies on large scales (e.g., A. Dressler & D. O. Richstone 1990; R. P. van der Marel 1994; E. Emsellem et al. 2004, 2014; J. D. Murphy et al. 2011; M. Sarzi et al. 2018), we focus on the most recent work (E. R. Liepold et al. 2023) and refer the reader there for a comparison of prior widefield kinematic measurements of M87. E. R. Liepold et al. (2023) used optical IFU data from Keck KCWI to extract stellar kinematics in 461 spatial bins from spectra with S/N ratios spanning 100–200. They fit between 3900 \AA and 5450 \AA and report eight GH moments over a $250'' \times 300''$ FOV, using pPXF and template stars from the MILES library (P. Sánchez-Blázquez et al. 2006; J. Falcón-Barroso et al. 2011) and an

⁷ <https://jwst-docs.stsci.edu/jwst-near-infrared-spectrograph/nirspec-instrumentation/nirspec-dispersers-and-filters>

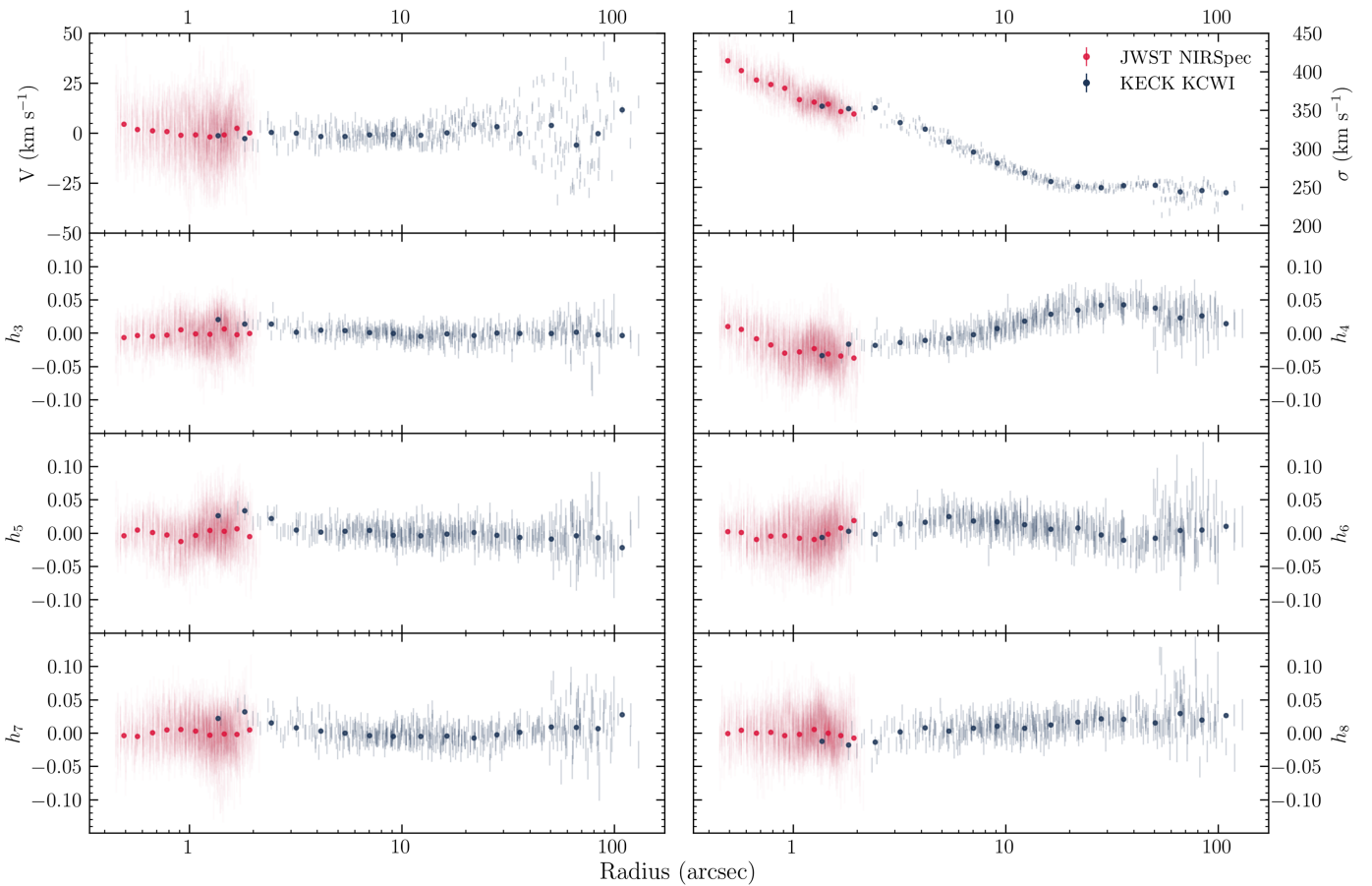


Figure 7. Juxtaposition of the small-scale NIRSpect measurements and the large-scale KCWI kinematics from E. R. Liepold et al. (2023). The data have been folded and are plotted as a function of projected distance from the nucleus, hence multiple position angles are depicted for these IFU data. The radius is shown in logarithmic scale, to encompass the wide spatial coverage of the KCWI dataset. The eight GH moments and uncertainties recovered from 2810 NIRSpect spatial bins (red lines) transition nicely to those extracted from the 461 KCWI bins (black lines). For clarity, the red and black points are average kinematic values from NIRSpect and KCWI, respectively, within radial bins. The NIRSpect and KCWI kinematics shown are not symmetrized.

additive Legendre polynomial degree of 1 and a multiplicative degree of 15.

In Figure 7, we show $V - h_8$ from NIRSpect in all 2810 bins and from KCWI in 461 bins. To better see radial trends, we also present the average kinematics within bins of projected radius. As is the case for the NIRSpect kinematics, we show the unsymmetrized KCWI kinematics with the (small) offsets in the odd-GH moments removed. We find that the small-scale NIRSpect kinematics nicely transition to the large-scale KCWI kinematics, including a continuation of the rapid rise in the velocity dispersion from $r \sim 20''$ toward the center of the galaxy. After thorough examination of the NIRSpect stellar kinematics described in Section 5.1, no additional manual adjustments were needed to bring the two sets of kinematics into agreement. This is particularly noteworthy, as the measurements were made from different telescopes/instruments, over distinct wavelength regimes, and using separate velocity template libraries.

While Figure 7 highlights the radial trends in the M87 stellar kinematics, there are important structures in the full 2D kinematic maps. For example, the KCWI velocity field is twisted, and from $60''$ outward there is a 25 km s^{-1} rotational pattern with a kinematic axis that is 40° misaligned with the galaxy’s photometric major axis. Consequently, E. R. Liepold et al. (2023) found that M87 has a strongly triaxial intrinsic shape. In a subsequent paper, we will combine the high-quality

small-scale NIRSpect and large-scale KCWI data and constrain triaxial orbit-based models (e.g., M. E. Quenneville et al. 2022) over an impressive $\sim 40\text{--}12,000$ pc extent.

6.2. Small-scale Measurements

Although there have been numerous large-scale stellar kinematic measurements made for M87 over the years, as well as gas-dynamical studies at the nucleus, extracting stellar kinematics at the center of M87 has proved challenging, due to the galaxy’s faint central surface brightness. There are only two prior high-angular-resolution studies of the stars within the central $\sim 1''$ of M87, coming from K. Gebhardt et al. (2011) and D. A. Simon et al. (2024), each employing different datasets and approaches. With AO Gemini NIFS data covering the first four K -band ^{12}CO bandheads, K. Gebhardt et al. (2011) measured nonparametric LOSVDs in 40 spatial bins over the same FOV as NIRSpect. The spatial binning was done assuming a particular major-axis position angle and yielded spectra with $S/N = 32\text{--}99$. K. Gebhardt et al. (2011) report that the inner Gaussian component of the NIFS PSF has an FWHM of $0''.08$ that contributes $\sim 40\%$ of the flux. Due to strong AGN contamination, nuclear spectra were discarded and the innermost kinematic measurement was made at $r \sim 0''.25$.

The top panel of Figure 8 compares our NIRSpect velocity dispersions with those from NIFS. Our fiducial kinematics

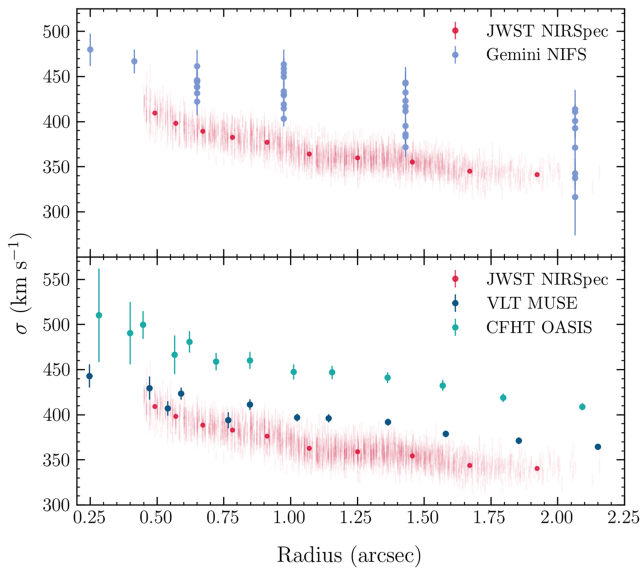


Figure 8. Comparison of the velocity dispersions measured from NIRSpec to those extracted from previous high-angular-resolution observations of M87. The data have been folded, and multiple position angles from the IFU observations are displayed. The 2810 NIRSpec velocity dispersions with uncertainties (red lines) are shown when fitting four (top) and two (bottom) GH moments, so that a fair comparison can be made to prior measurements in the literature. The red points denote the average NIRSpec kinematic values within radial bins. Top: the blue points with error bars are the velocity dispersions measured within 40 bins from AO NIFS data (K. Gebhardt et al. 2011). Bottom: the velocity dispersions from AO NFM MUSE (navy) and good-seeing OASIS (teal) data, shown over the radial extent of NIRSpec, come from the averages within radial bins from D. A. Simon et al. (2024).

include measurements of $V - h_8$; however, to properly compare to the NIFS data, we refit the NIRSpec spectra in the same way as described in Section 5 but instead use four GH moments to parameterize the LOSVD. Likewise, K. Gebhardt et al. (2011) took their best-fit nonparametric LOSVDs, characterized them with a GH series up to h_4 , and provided the moments in each of the spatial bins beyond $r \sim 0''.25$ in their Table 2.

More recently, D. A. Simon et al. (2024) extracted stellar kinematics from new AO VLT MUSE observations with a PSF FWHM of $0''.049$ and older good-seeing CFHT OASIS data with a PSF FWHM of $0''.561$ (originally from R. M. McDermid et al. 2006). Both datasets cover optical wavelengths $\sim 4800\text{\AA} - 5500\text{\AA}$ and have FOVs of $7''.5 \times 7''.5$ and $10'' \times 8''$, respectively. D. A. Simon et al. (2024) spatially binned each dataset to reach $S/N \sim 50$ and assumed a Gaussian LOSVD, with the V fixed to the recessional velocity of M87. Thus, only σ was measured with pPXF.

In the bottom panel of Figure 8, we show our NIRSpec kinematics along with those from MUSE and OASIS. To compare with D. A. Simon et al. (2024), we refit the NIRSpec spectra following the methods in Section 5 but this time fitting just V and σ . D. A. Simon et al. (2024) found that the extracted σ from both MUSE and OASIS were highly sensitive to the wavelength region fit and the additive polynomial degree used to adjust the template stars. In Figure 8, we plot the MUSE and OASIS points as shown in the bottom panel of Figure 5 of D. A. Simon et al. (2024), which are their “RNI” degree 1 kinematics averaged in radial bins. In addition, D. A. Simon et al. (2024) found their MUSE and OASIS velocity dispersions were systematically above the large-scale

SAURON kinematics of M87 (E. Emsellem et al. 2004; M. Cappellari et al. 2011) over the common radial range of the datasets. To enforce a smooth transition to the SAURON kinematics, D. A. Simon et al. (2024) scaled their initial MUSE and OASIS velocity dispersions downward, before running their main Jeans-based stellar-dynamical model. We note that we show the unscaled original measurements of the MUSE and OASIS dispersions in Figure 8.

As can be seen in Figure 8, the velocity dispersion from NIFS is systematically above the NIRSpec dispersions at all radii by an average of $\sim 50\text{ km s}^{-1}$, or $\sim 15\%$ of the NIRSpec value. Similarly, the velocity dispersions from MUSE and OASIS are systematically larger than the NIRSpec dispersions by averages of $\sim 30\text{ km s}^{-1}$ and $\sim 90\text{ km s}^{-1}$, or $\sim 10\%$ and $\sim 25\%$ of the NIRSpec value, respectively, over the radial range covered by NIRSpec. The velocity dispersions from MUSE and OASIS, scaled by D. A. Simon et al. (2024; not shown in Figure 8), are more similar to the NIRSpec values, generally falling at the upper end of the 1σ uncertainties on the NIRSpec velocity dispersions. All four datasets (NIRSpec, NIFS, MUSE, and OASIS) exhibit a central rise in the velocity dispersion.

While the broad radial trends among the high-angular-resolution datasets are analogous, the NIRSpec data provide a much improved kinematic view of the center of M87. With the NIRSpec data, there is a dramatic increase in the number of spatial bins, a substantial improvement in the S/N ratio, and far more detailed characterization of the LOSVDs. JWST’s unique combination of sharp angular resolution, enhanced sensitivity, and reduced background has opened a new window onto the stellar dynamics at the centers of nearby massive galaxies with diffuse cores—systems that were previously difficult to probe in detail.

7. Conclusion

We present new stellar kinematic measurements of the central region of M87 using the JWST NIRSpec IFU with excellent S/N ratios over the K -band CO bandheads. These observations significantly improve upon prior ground-based high-angular-resolution datasets of M87 and provide detailed stellar kinematics in the immediate environment around the SMBH.

We carefully examine the default JWST reduction pipeline and implement a couple of modifications to enhance the DQ. In particular, we mask artifacts in each of the 16 dithered 2D calibrated images and we assemble the merged data cube in such a way that minimizes extreme positive and negative artifacts, especially near the NRS1/NRS2 detector gap. Hence, the integrity of the spectra is maintained and robust stellar kinematics can be determined from the CO bandheads.

We conduct an in-depth exploration of the most appropriate way to extract the M87 stellar kinematics from the CO bandheads on the NRS1 detector. After exploring two empirical velocity template libraries (K2 OSIRIS and Winge GNIRS), to complement the main (synthetic) library we use (PHOENIX), we find consistent kinematics when masking Ca I just blueward of the CO bandheads. The K2 OSIRIS and Winge GNIRS libraries are velocity template spectra that have not yet been used for NIRSpec kinematic studies, but they are libraries that have been employed for near-infrared AO IFU data in the past. PHOENIX has been the library of choice for kinematic studies of local galaxies with NIRSpec. For M87,

we notice that the PHOENIX library struggles to fully reproduce the Ca I feature, and the even-GH moments are biased low when Ca I is included in the spectral fit. The K2 OSIRIS and Winge GNIRS libraries are able to match the observed Ca I, and there is no difference in the inferred GH moments when the feature is fit versus when it is masked. Our final kinematics come from using the PHOENIX library with Ca I masked.

In the case of M87, we find that the degree of the polynomial applied to the LOSVD-convolved template stars has an impact on the inferred even-GH moments. With a larger fitting window covering four CO bandheads before the detector gap, a multiplicative polynomial of at least degree 3 is needed to prevent biased even moments. For the spatial bins with spectra exhibiting two or three CO bandheads before the detector gap, any degree (1–6) for the multiplicative polynomial returns consistent results. Since the wavelength range we fit over, and the number of CO bandheads before the detector gap, vary over the NIRSspec FOV, using too low a polynomial degree yields even-GH moments that are too large in only a portion of the IFU, creating an artificial gradient. We adopt a degree 3 multiplicative polynomial to produce secure GH moments and kinematic maps with real spatial trends. Thus, when working with high-S/N ratio NIRSspec data, we recommend using different template libraries, with attention paid to the fit of the Ca I line and an examination of the polynomial degree (or, equivalently, how the galaxy continuum is modeled).

The M87 NIRSspec stellar kinematics transition seamlessly to the most recently published large-scale kinematics from KCWI, providing continuous coverage from the central parsecs to several kiloparsec scales. Together, we expect these datasets to enable tight constraints on the M87 M_{BH} , stellar mass-to-light ratio, dark matter halo, galaxy intrinsic shape, and orbital distribution throughout the galaxy and especially near the SMBH. Future work will apply the most general triaxial stellar-dynamical models to the NIRSspec and KCWI kinematics, cementing M87 at the upper end of the SMBH –galaxy relations and aiding in our understanding of SMBH and galaxy coevolution.

Acknowledgments

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Facility: JWST (NIRSspec).

Software: astropy (Astropy Collaboration et al. 2013, 2018, 2022), JWST Science Calibration Pipeline (H. Bushouse et al.

2023), matplotlib (J. D. Hunter 2007), numpy (C. R. Harris et al. 2020), pPXF (M. Cappellari 2023), scipy (P. Virtanen et al. 2020), vorbin (M. Cappellari & Y. Copin 2003).

ORCID iDs

Refa M. Al-Amri  <https://orcid.org/0009-0008-8003-1048>
 Jonelle L. Walsh  <https://orcid.org/0000-0002-1881-5908>
 Emily R. Liepold  <https://orcid.org/0000-0002-7703-7077>
 Chung-Pei Ma  <https://orcid.org/0000-0002-4430-102X>
 Jenny E. Greene  <https://orcid.org/0000-0002-5612-3427>

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